

In the Claims:

Please cancel claim 4-6, 16-18, and 20 without prejudice.

Please amend claims 1, 7, 8, 13-15, 19, and 21 as follows:

1. (currently amended) A method for implementing device selection in a robotic media library with multiple media types and multiple device types comprising the steps of:

storing a first indicator with predefined media information to identify a required technology for each media;

identifying an operation request to the robotic media library;

responsive to said operation request, checking for multiple device types in the robotic media library;

responsive to identifying the multiple device types in the robotic media library and a default value for said first indicator, selecting a first device type including selecting a newest device type in the robotic media library for said first device type; and

selecting a device of said selected first device type and pacing media in said selected device; and

responsive to media being placed in said selected device, checking for successful operation, and responsive to an unsuccessful operation, selecting a next device type.

2. (original) A method for implementing device selection in a robotic media library as recited in claim 1 includes the steps responsive to said operation request, of setting a device type from said predefined media information.

3. (original) A method for implementing device selection in a robotic media library as recited in claim 1 wherein the step, responsive to identifying the multiple device types in the robotic media library and a default value for said first indicator, of selecting said first device type includes the steps of storing a value representing said first device type for said first indicator.

Claims 4-6. (canceled)

7. (currently amended) A method for implementing device selection in a robotic media library as recited in claim 1 ~~claim 6~~ wherein the step of selecting said next device type includes the steps of selecting a next oldest device type in the robotic media library for said next device type.

8. (currently amended) A method for implementing device selection in a robotic media library as recited in claim 1 ~~claim 6~~ includes the steps of selecting a second device of said selected next device type, placing media in said selected second device.

9. (original) A method for implementing device selection in a robotic media library as recited in claim 8 further includes the steps of checking for successful operation, and responsive to an unsuccessful operation, selecting a next device type.

10. (original) A method for implementing device selection in a robotic media library as recited in claim 8 further includes the steps of checking for successful operation, and responsive to said successful operation, continuing with a requested operation.

11. (original) A method for implementing device selection in a robotic media library as recited in claim 1 includes the steps of storing a second indicator to describe each said device in said robotic media library.

12. (original) A method for implementing device selection in a robotic media library as recited in claim 11 includes the steps of storing said second indicator with predefined information for each said device in said robotic media library.

13. (currently amended) A computer-readable medium encoded with a computer program product for implementing device selection in a robotic media library in a computer system, said computer program product including instructions executed by the computer system to cause the computer system to perform the steps of:

storing a first indicator with predefined media information to identify a required technology for each media;

identifying an operation request to the robotic media library;

responsive to said operation request, checking for multiple device types in the robotic media library;

responsive to identifying the multiple device types in the robotic media library and a default value for said first indicator, selecting a first device type including selecting a newest device type in the robotic media library for said first device type; and

selecting a device of said selected first device type and pacing media in said selected device; and

responsive to media being placed in said selected device, checking for

successful operation, and responsive to an unsuccessful operation, selecting a next device type.

14. (currently amended) A computer-readable medium encoded with a computer program product for implementing device selection as recited in claim 13 includes the steps responsive to said operation request, of setting a device type from said predefined media information.

15. (currently amended) A computer-readable medium encoded with a computer program product for implementing device selection as recited in claim 13 wherein the step of selecting said first device type includes the steps of storing a value representing said first device type for said first indicator.

Claims 16-18. (canceled)

19. (currently amended) Apparatus in a computer system for implementing device selection in a robotic media library comprising:

a computer-readable medium encoded with a stored media information;
said computer-readable medium encoded with a first indicator stored with predefined media information to identify a required technology for each media;
said computer-readable medium encoded with a device selection control program, said device selection control program including instructions executed by the computer system to cause the computer system to perform the steps of ~~for~~ identifying an operation request to the robotic media library; responsive to said operation request, ~~for~~ checking for multiple device types in the robotic media library; responsive to identifying the multiple device types in the robotic media library and a default value for

said first indicator, ~~for~~ selecting a first device type including selecting a newest device type in the robotic media library for said first device type; and ~~for~~ selecting a device of said selected first device type and pacing media in said selected device; and

said device selection control program responsive to media being placed in said selected device, performing checking for successful operation, and responsive to an unsuccessful operation, selecting a next device type.

20. (canceled)

21. (currently amended) Apparatus for implementing device selection in a robotic media library as recited in claim 19 wherein said device selection control program responsive to ~~media being placed in said selected device, performs checking for successful operation, and responsive to~~ said successful operation, continues with a requested operation.

22. (original) Apparatus for implementing device selection in a robotic media library as recited in claim 19 wherein said device selection control program stores a second indicator to describe each said device in said robotic media library.